

# Leveraging Large Language Models (LLMs) for Interpreting Datasets of Autonomous and Semi-Autonomous Vehicles

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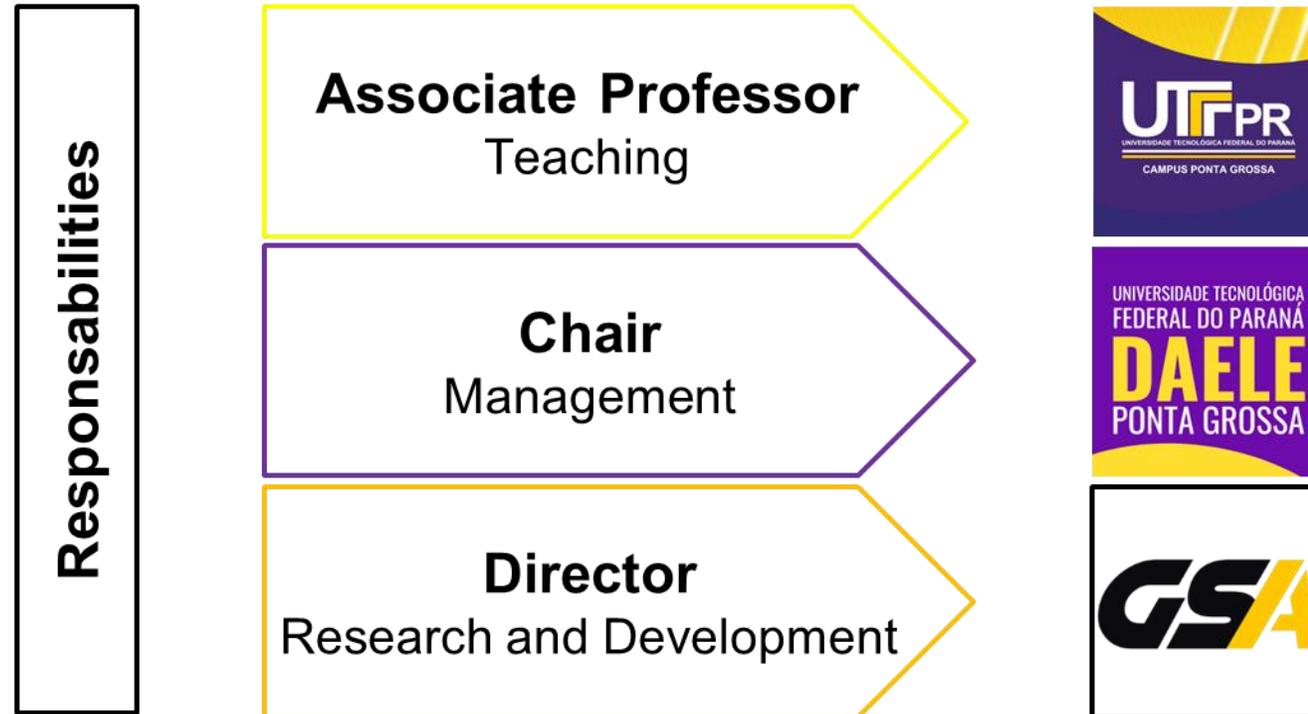
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# Summary

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2. Context and Motivation
3. Why are LLM and SLM so good for Mobility?
4. ADAS → IDAS → SDAS → FAS
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11. Challenges and Limitations
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# ADAS

Reactive



senses and reacts

# IDAS

Adaptive



understands and learns

# SDAS

Collaborative



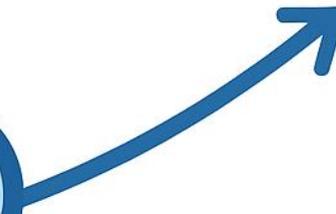
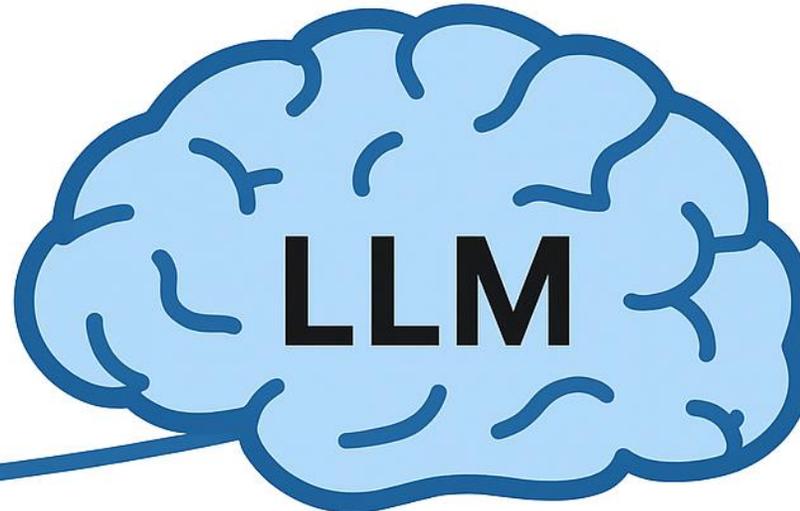
communicates and optimizes

# FAS

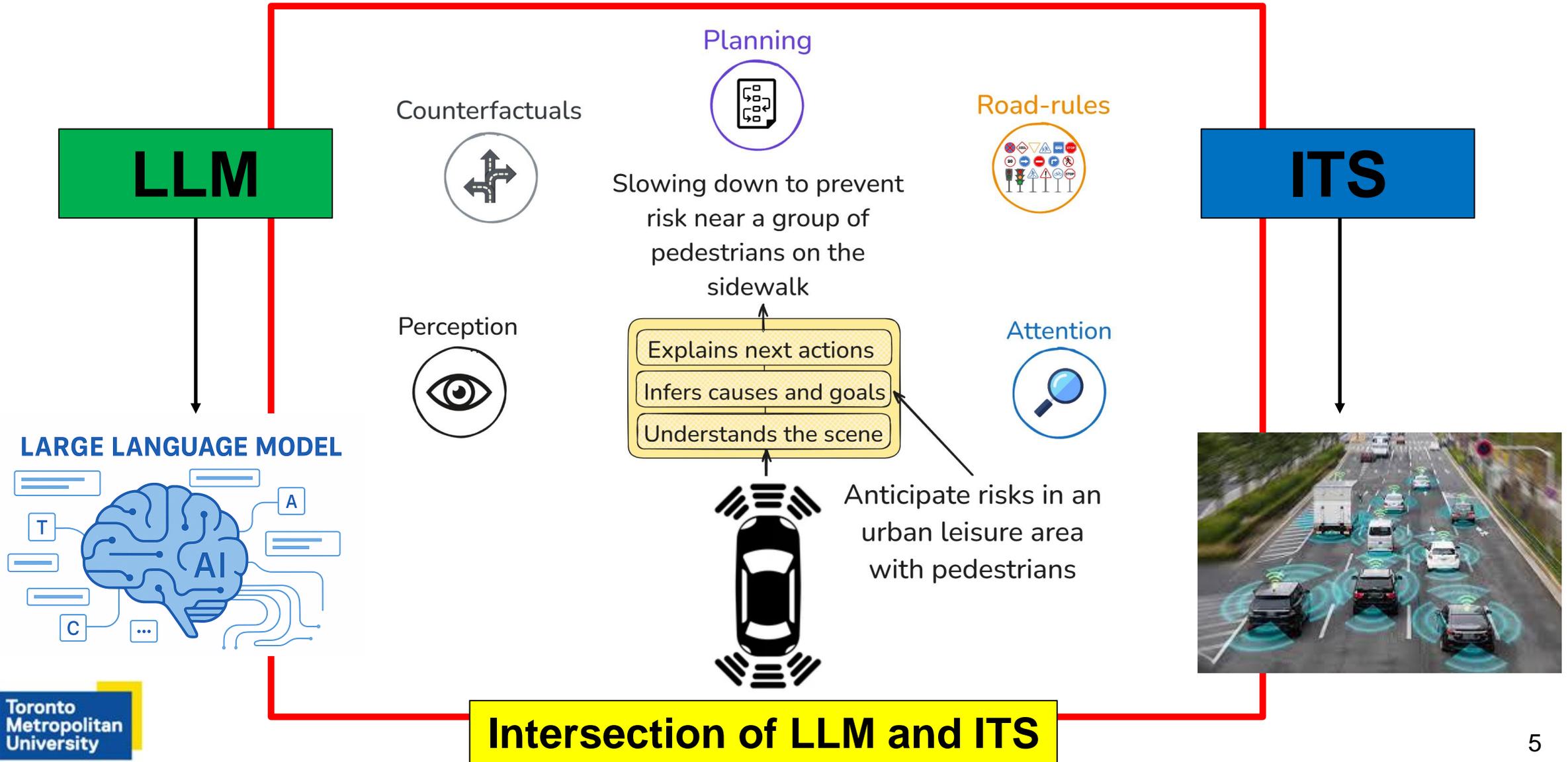
Autonomous



decides and drives independently

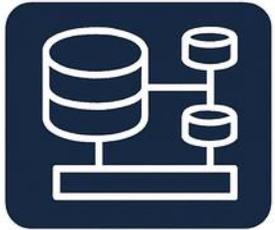


# 1. Introduction



## 2. Context and Motivation

Autonomous and semi-autonomous vehicles must operate safely in dynamic, uncertain environments, where robust data interpretation is essential.



**Datasets** are too large and heterogeneous to analyze manually



**Complex interactions** between sensors create ambiguity or conflicting evidence

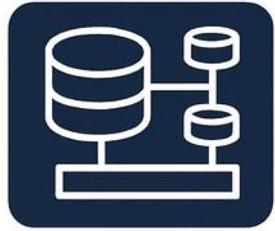


Safety validation requires **interpreting rare or edge-case scenarios** that are difficult to capture



Regulatory bodies demand **transparent and explainable justifications** for vehicle behavior

# 2. Context and Motivation



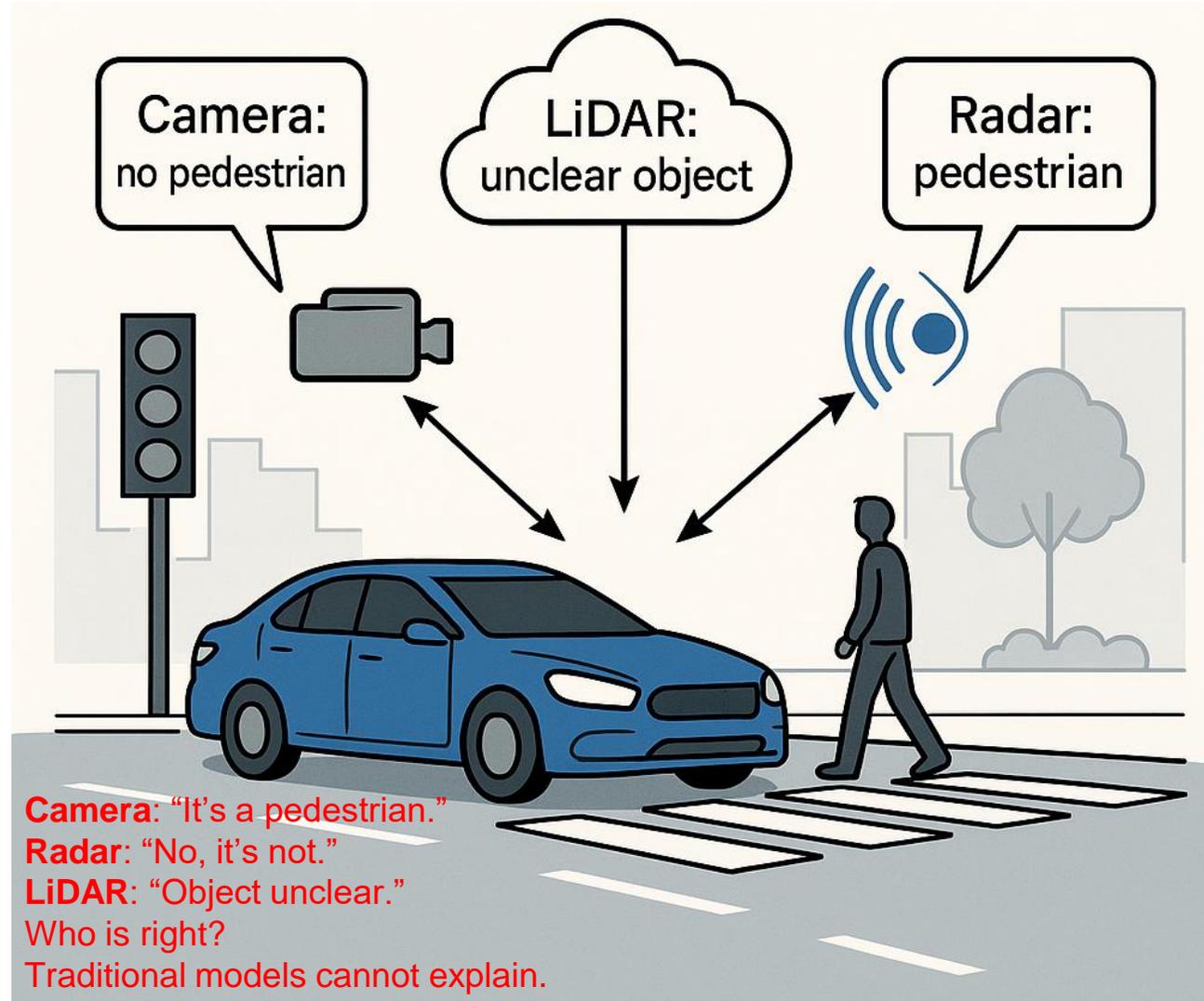
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## 2. Context and Motivation



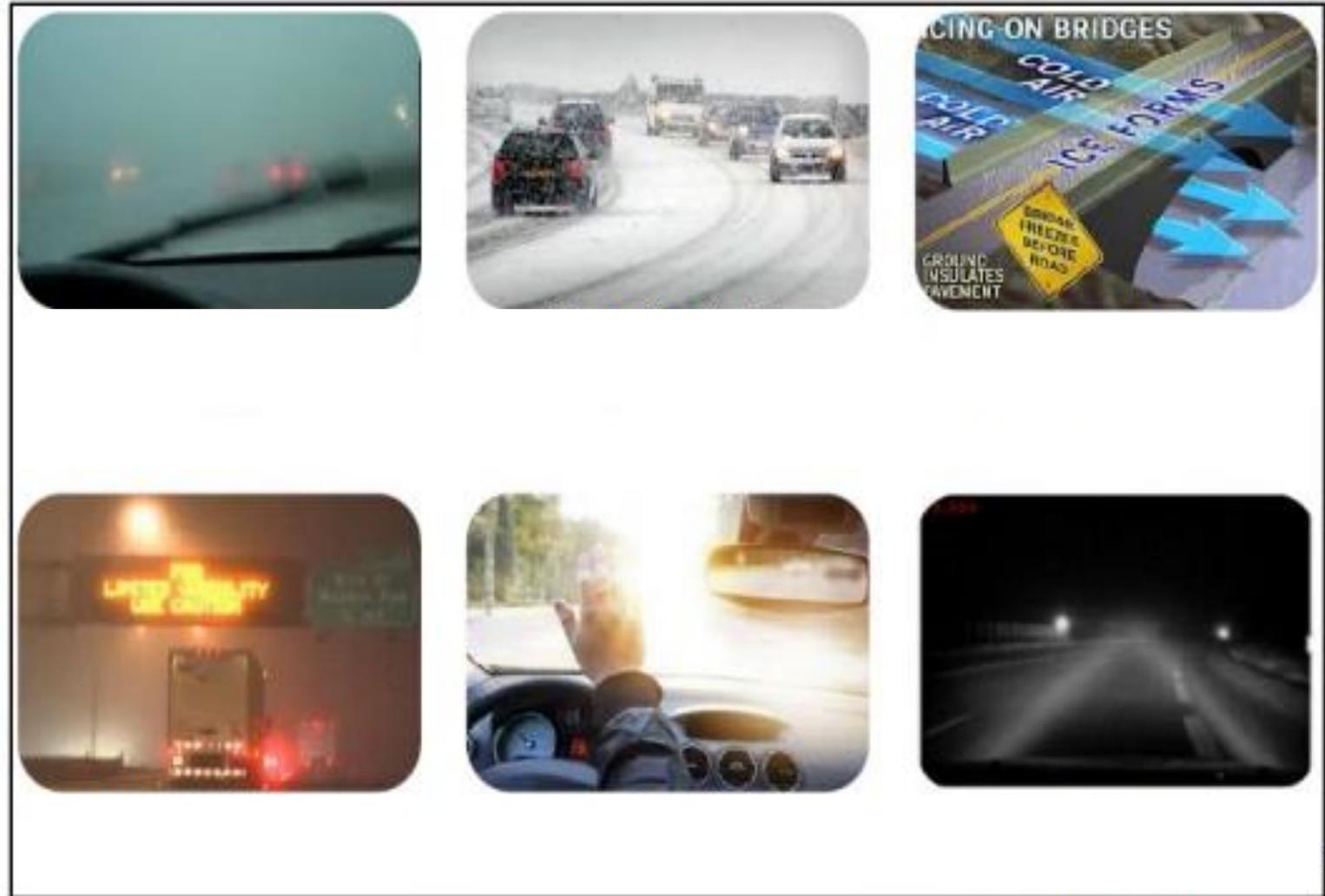
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## 2. Context and Motivation



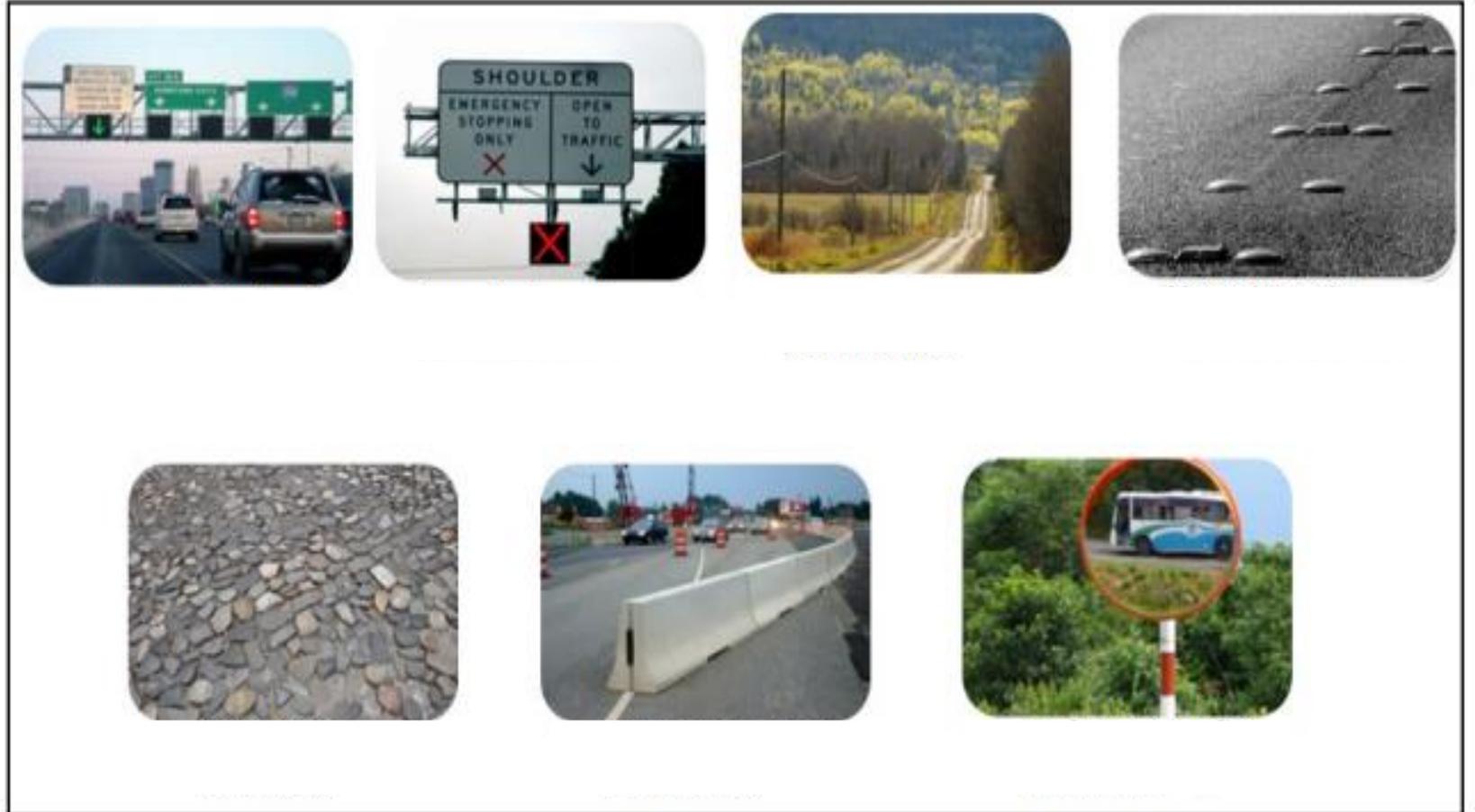
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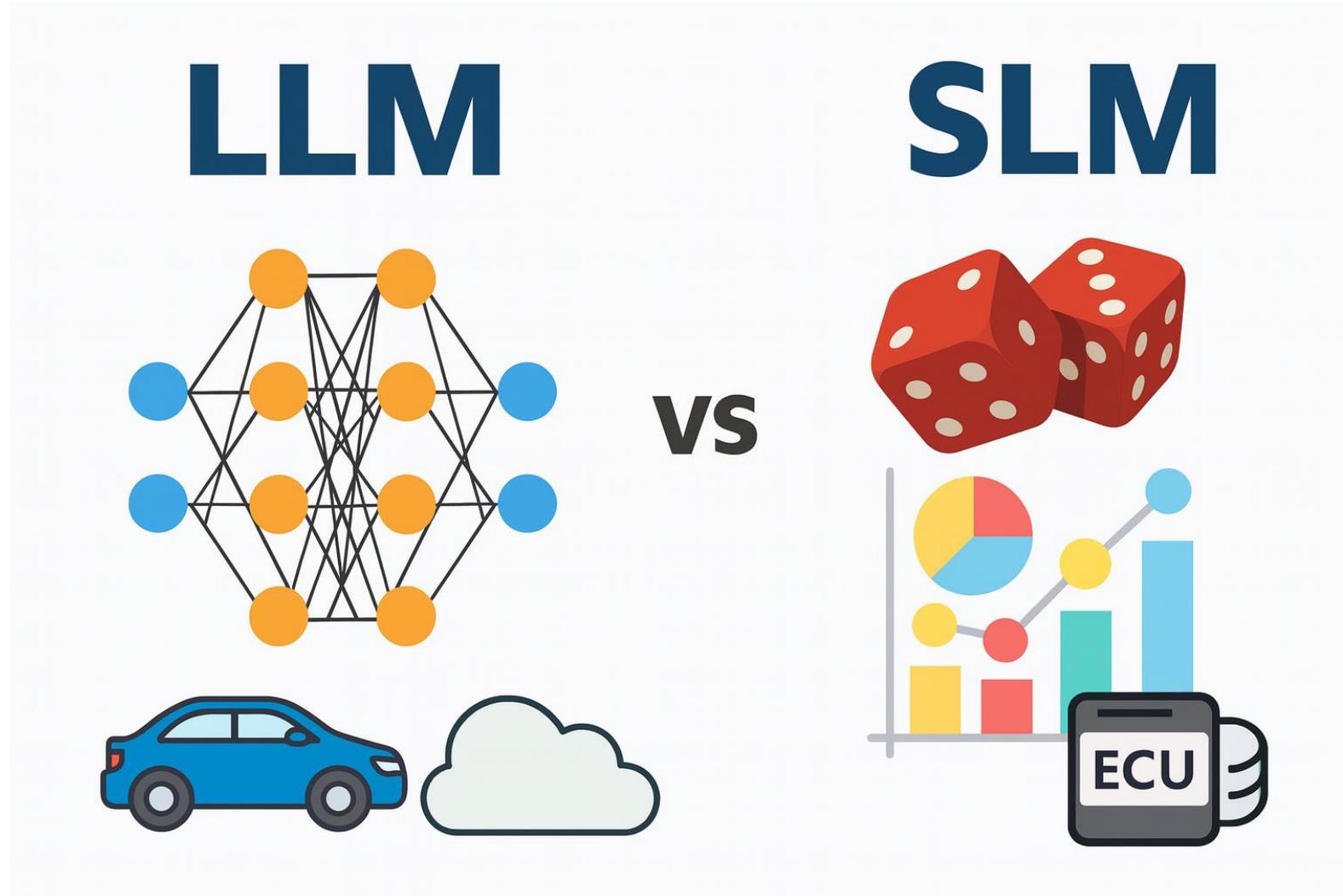
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Regulatory bodies demand **transparent and explainable justifications** for vehicle behavior

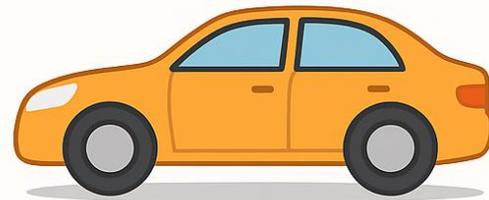
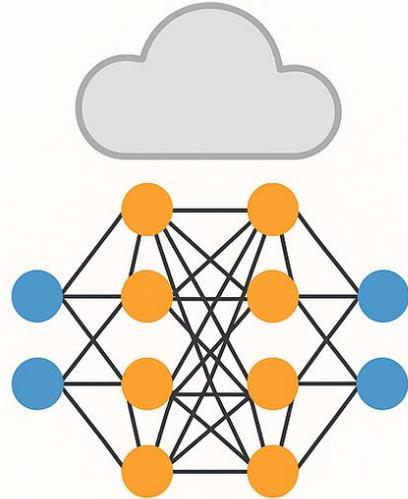


### 3. Why are LLM and SLM so good for Mobility?



### 3. Why are LLM and SLM so good for Mobility?

## LLM



## SLM



**VS**

#### Cloud

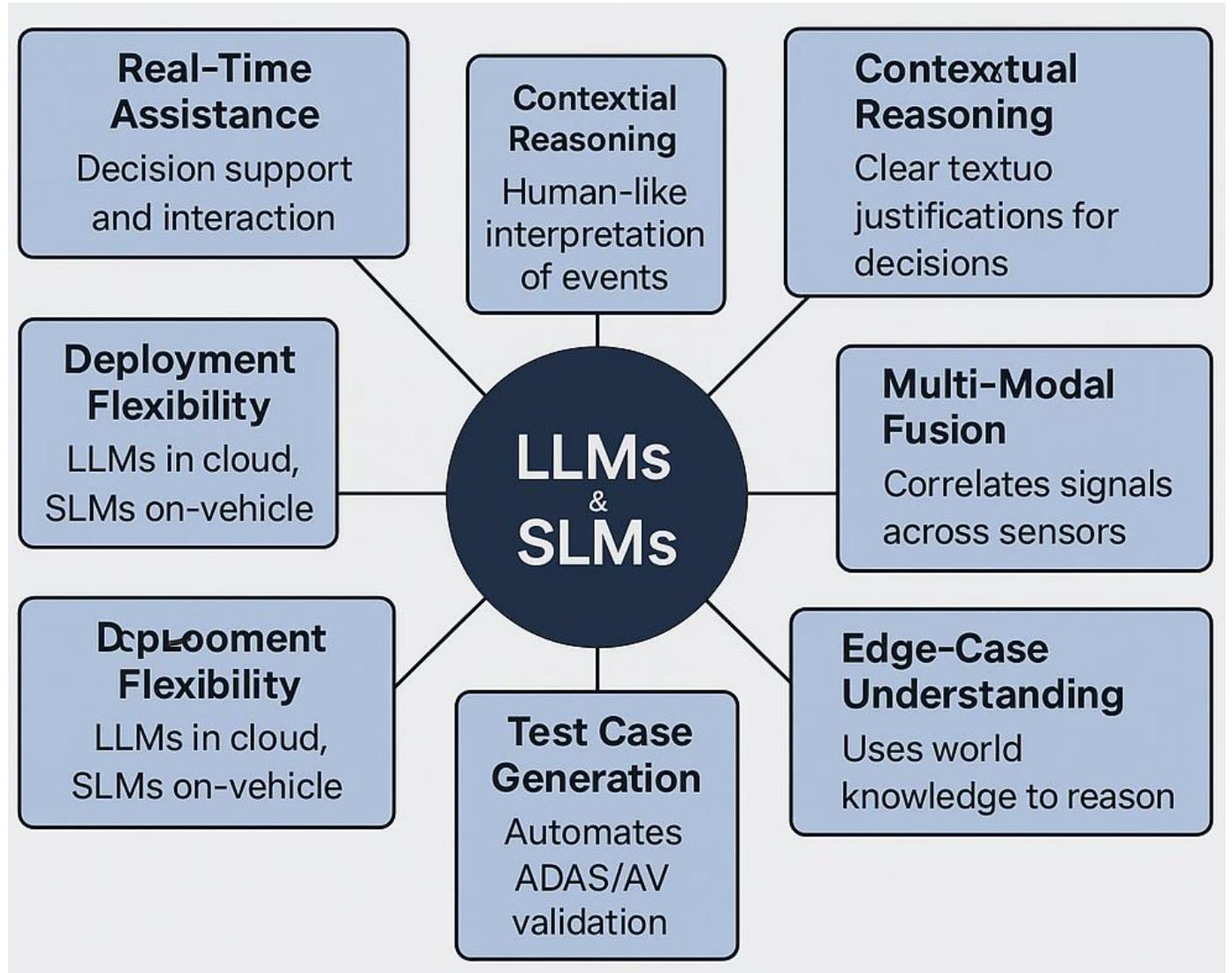
- Large scale
- High latency
- General purpose

#### Edge

- Small scale
- Low latency
- Specific task

# 3. Why are LLM and SLM so good for Mobility?

LLMs and SLMs bring human-like reasoning, explanation, and semantic understanding to complex automotive data - closing the gap between perception and high-level decision-making, and enabling safer, more transparent mobility.



## 4. ADAS → IDAS → SDAS → FAS

**Advanced Driver Assistance Systems (ADAS)** enhance driving safety through precise sensing and control.

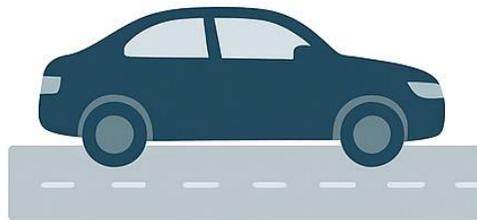
**Intelligent Driver Assistance Systems (IDAS)** evolve this paradigm by embedding artificial intelligence for perception, reasoning, and personalization.

**Smart Driver Assistance Systems (SDAS)** extend intelligence through connectivity and cooperative learning, creating an ecosystem of vehicles that share, adapt, and optimize in real time.

# 4. ADAS → IDAS → SDAS → FAS

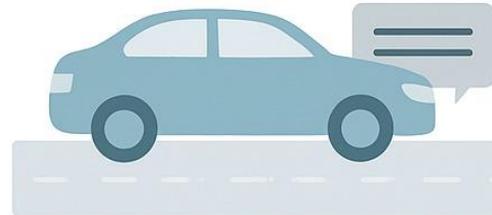
**xDAS**  
Everything  
Driver  
Assistance  
Systems

## ADVANCED DRIVER ASSISTANCE SYSTEMS



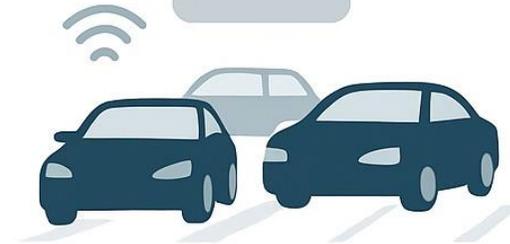
enhance driving safety  
through precise  
sensing and control

## INTELLIGENT DRIVER ASSISTANCE SYSTEMS



evolve this paradigm by  
embedding artificial  
intelligence for  
perception, reasoning,  
and personalization

## SMART DRIVER ASSISTANCE SYSTEMS

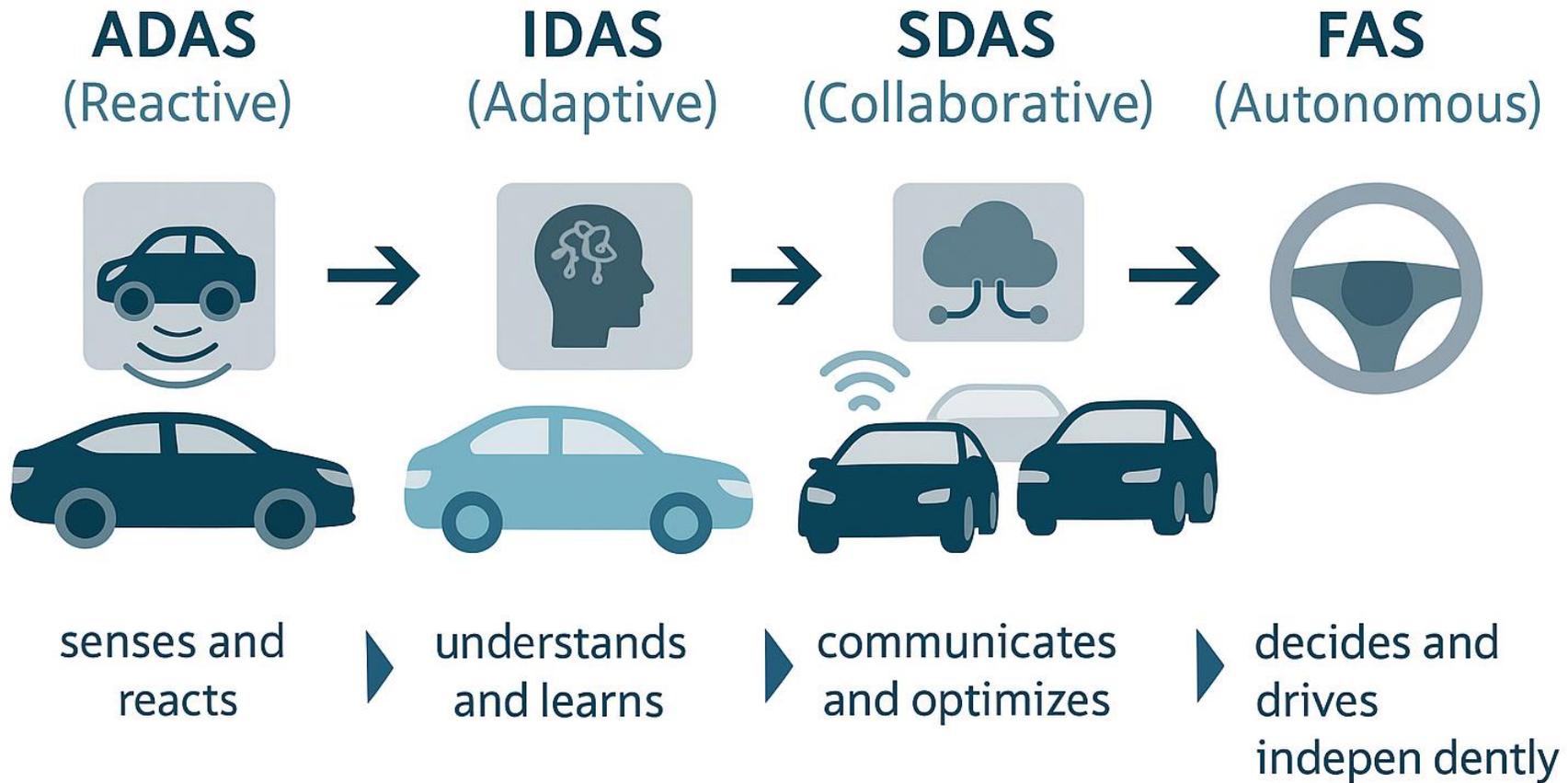


extend intelligence through  
connectivity and  
cooperative learning,  
creating an ecosystem of  
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and optimize in real time

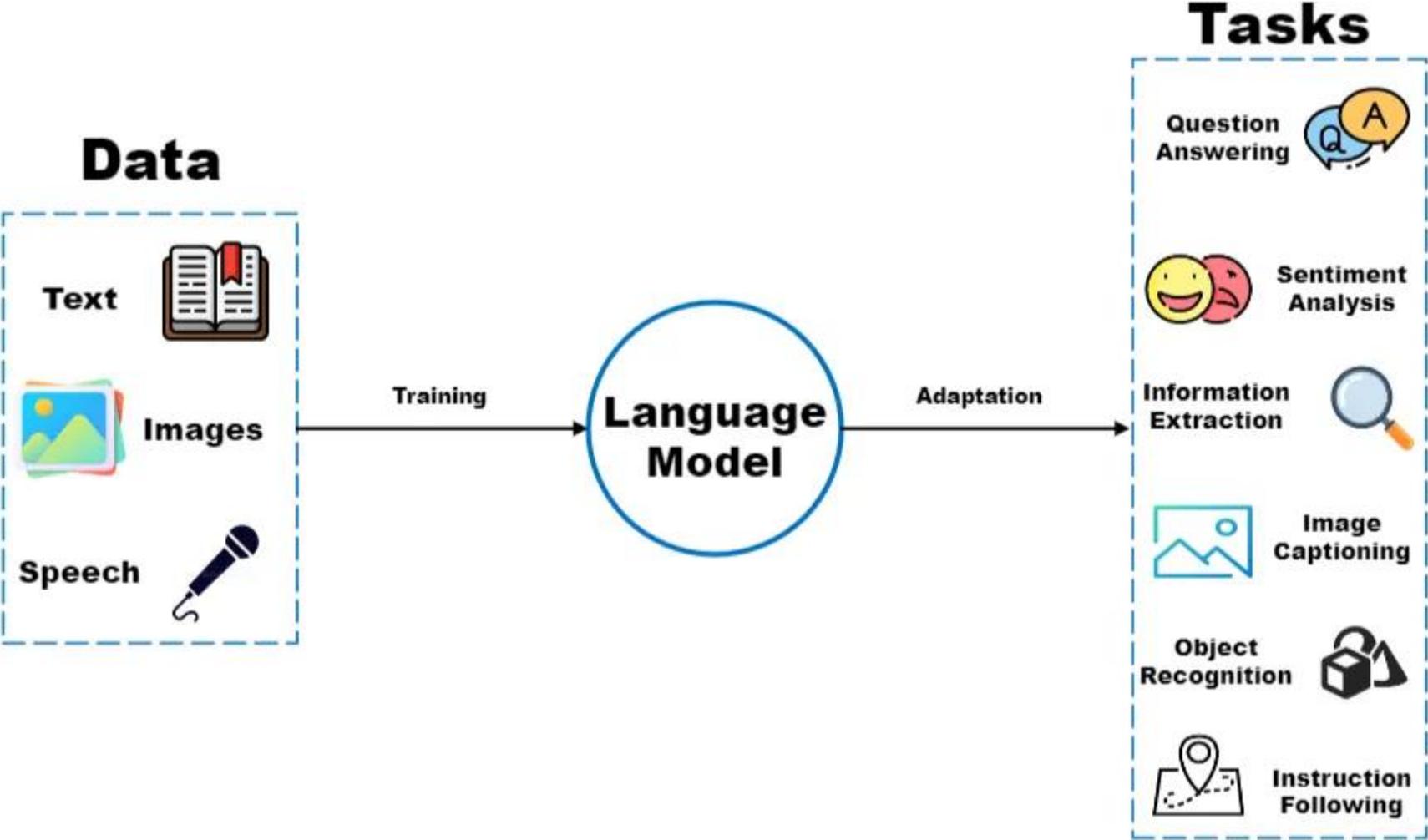
# 4. ADAS → IDAS → SDAS → FAS

| Feature                 | ADAS                        | IDAS   | SDAS   |
|-------------------------|-----------------------------|--|--|
| <b>Core Concept</b>     | Advanced sensing & control  | AI reasoning & learning                            | Connected, cooperative, and predictive AI      |
| <b>Decision Logic</b>   | Deterministic / rule-based  | Cognitive / adaptive                               | Collective / distributed                       |
| <b>Data Source</b>      | Local sensors               | Sensors + driver + context                         | Sensors + V2X + cloud                          |
| <b>AI Integration</b>   | Minimal (mostly perception) | Deep integration (perception, planning, reasoning) | Integrated across vehicles and infrastructure  |
| <b>Learning Ability</b> | None (fixed logic)          | Online/offline learning                            | Shared / federated learning                    |
| <b>Communication</b>    | Isolated vehicle            | Context-aware vehicle                              | Connected ecosystem                            |
| <b>Objective</b>        | Driver assistance & safety  | Intelligent support & personalization              | System-level optimization & coordination       |
| <b>Example Features</b> | ACC, LKA, AEB               | Predictive ACC, AI co-pilot                        | Cooperative ACC, cloud-based hazard prediction |

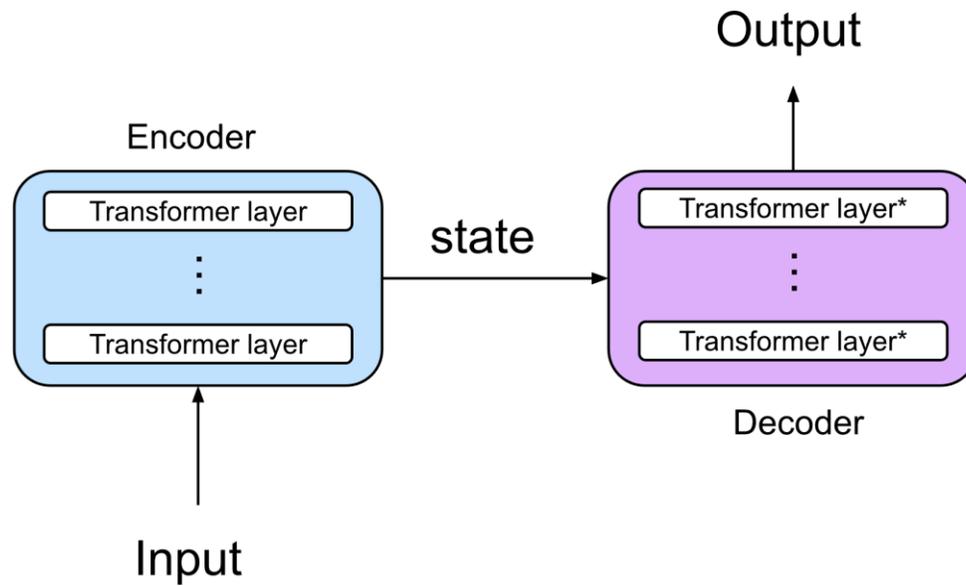
# 4. ADAS → IDAS → SDAS → FAS



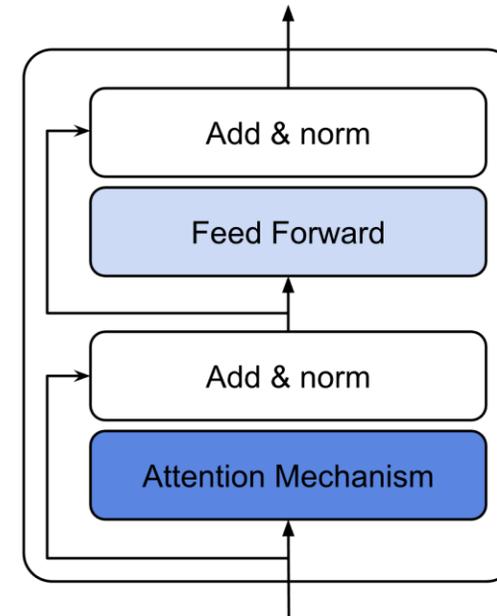
# 5. Foundations of Large Language Model



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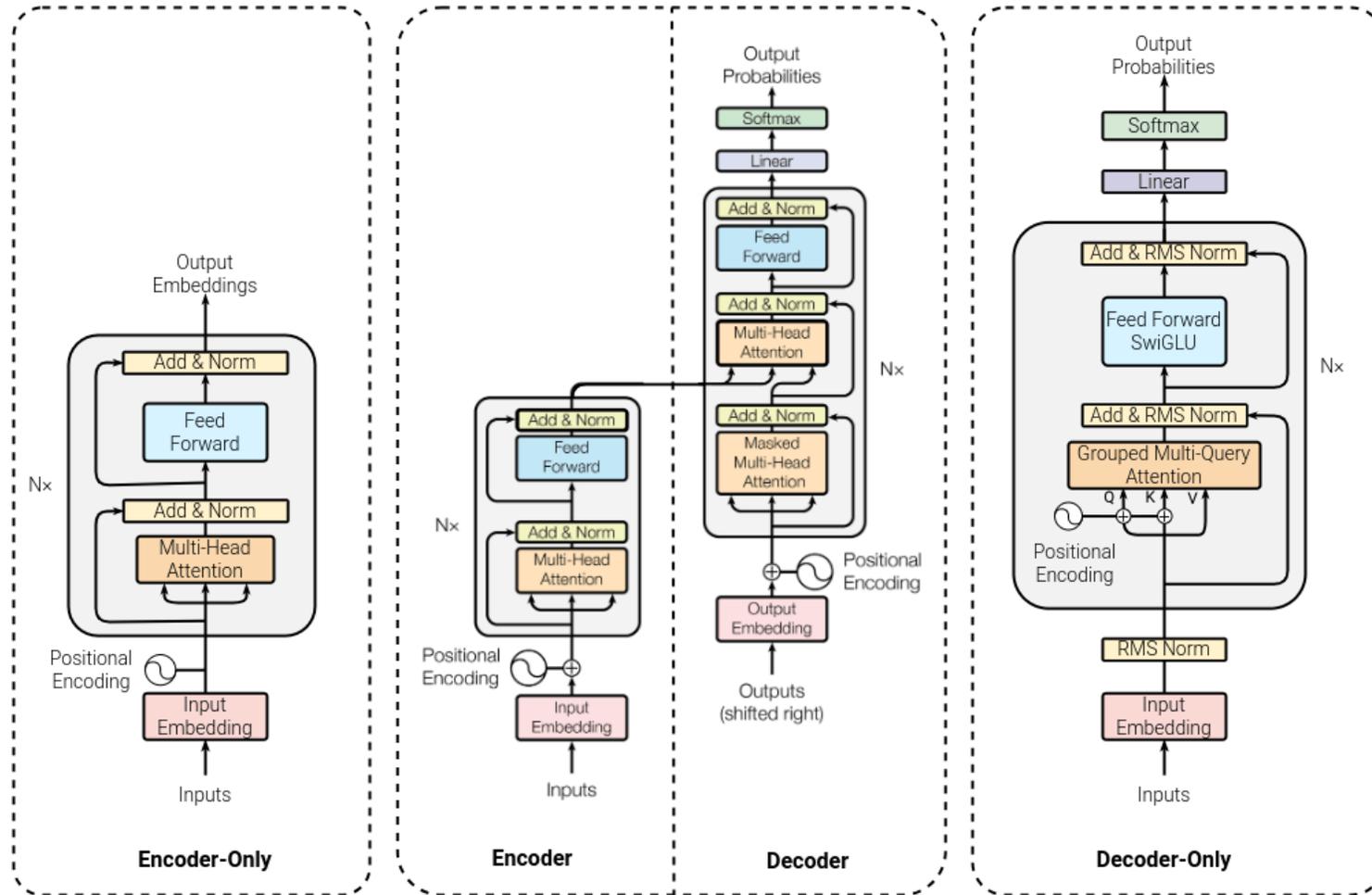


(a)



(b)

# 5. Foundations of Large Language Model



**BERT**  
(Devlin et al., 2018)

**Original Transformer**  
(Vaswani et al., 2017)

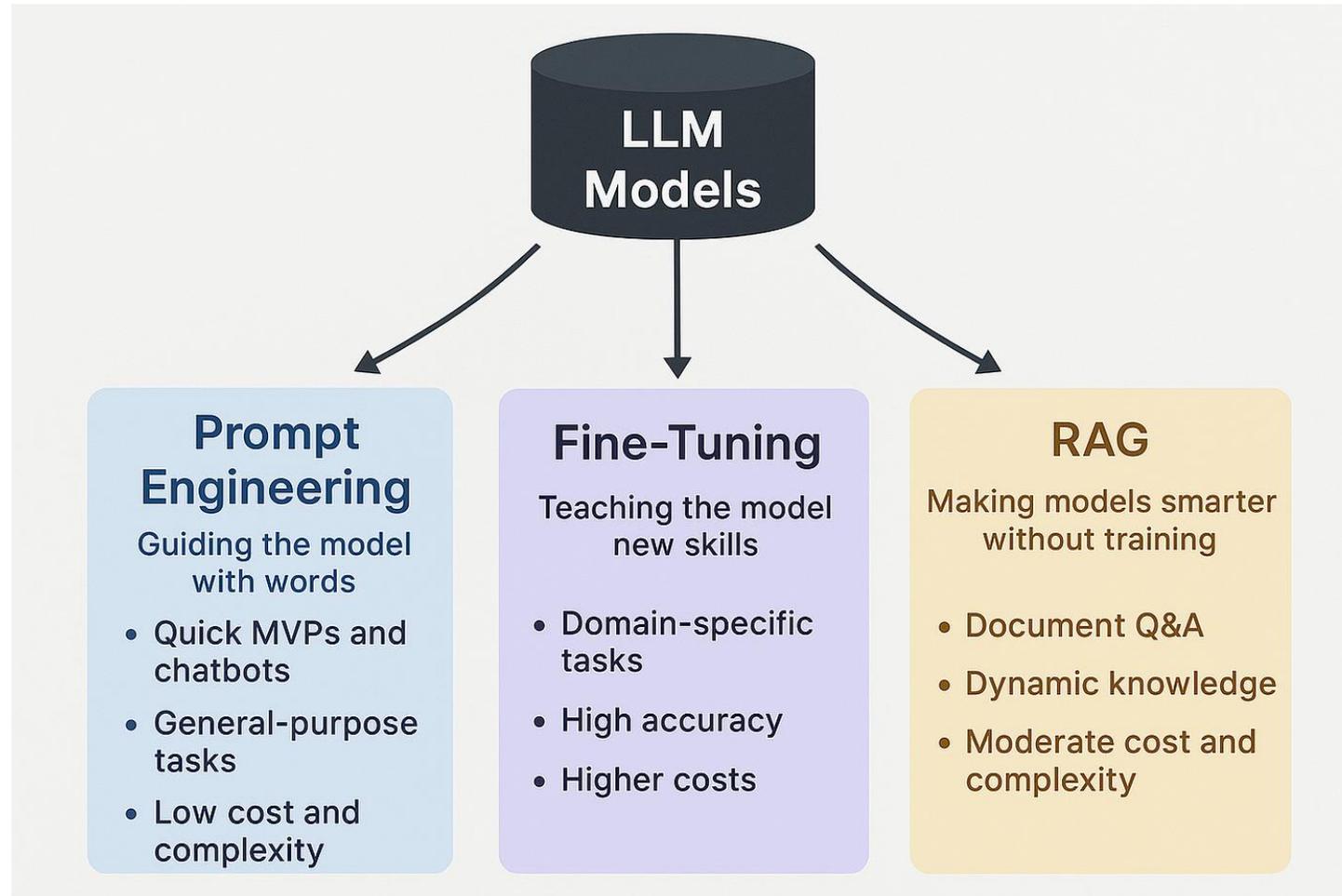
**LLaMA**  
(Touvron et al., 2023)

# 5. Foundations of Large Language Model

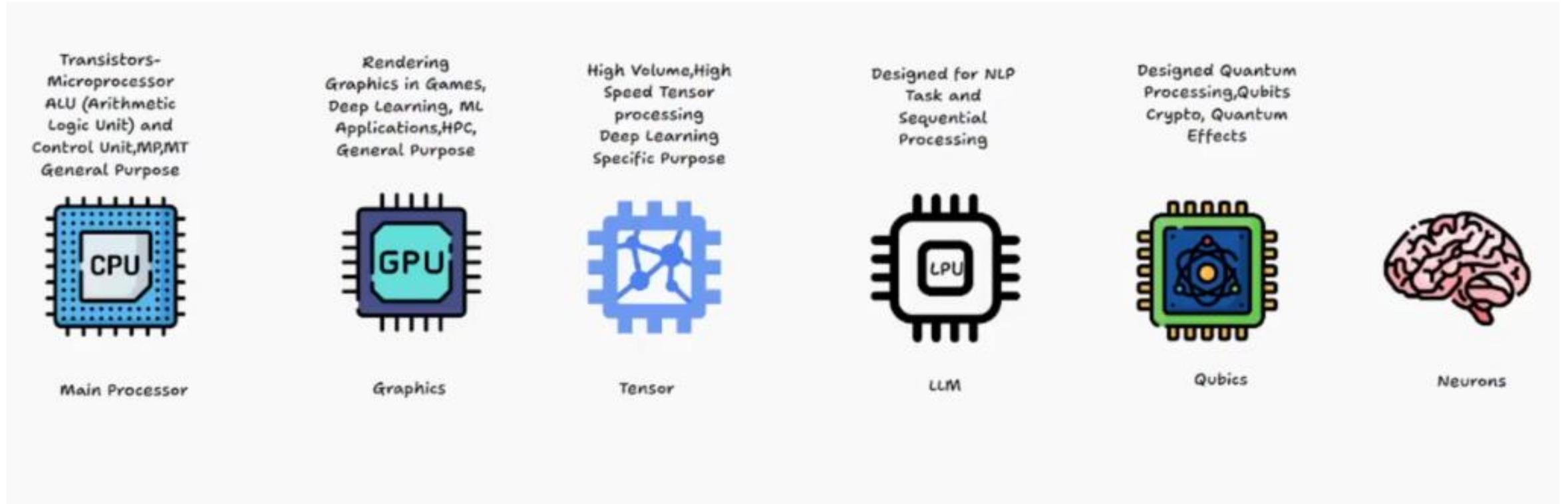
## Large Language Models (LLMs) in three levels:

- **Prompt Engineering** – using pre-trained LLMs with structured prompts.
- **Model Fine-Tuning** – adapting LLMs to domain-specific datasets.
- **Build Your Own** – creating a customized LLM for autonomous vehicle data.

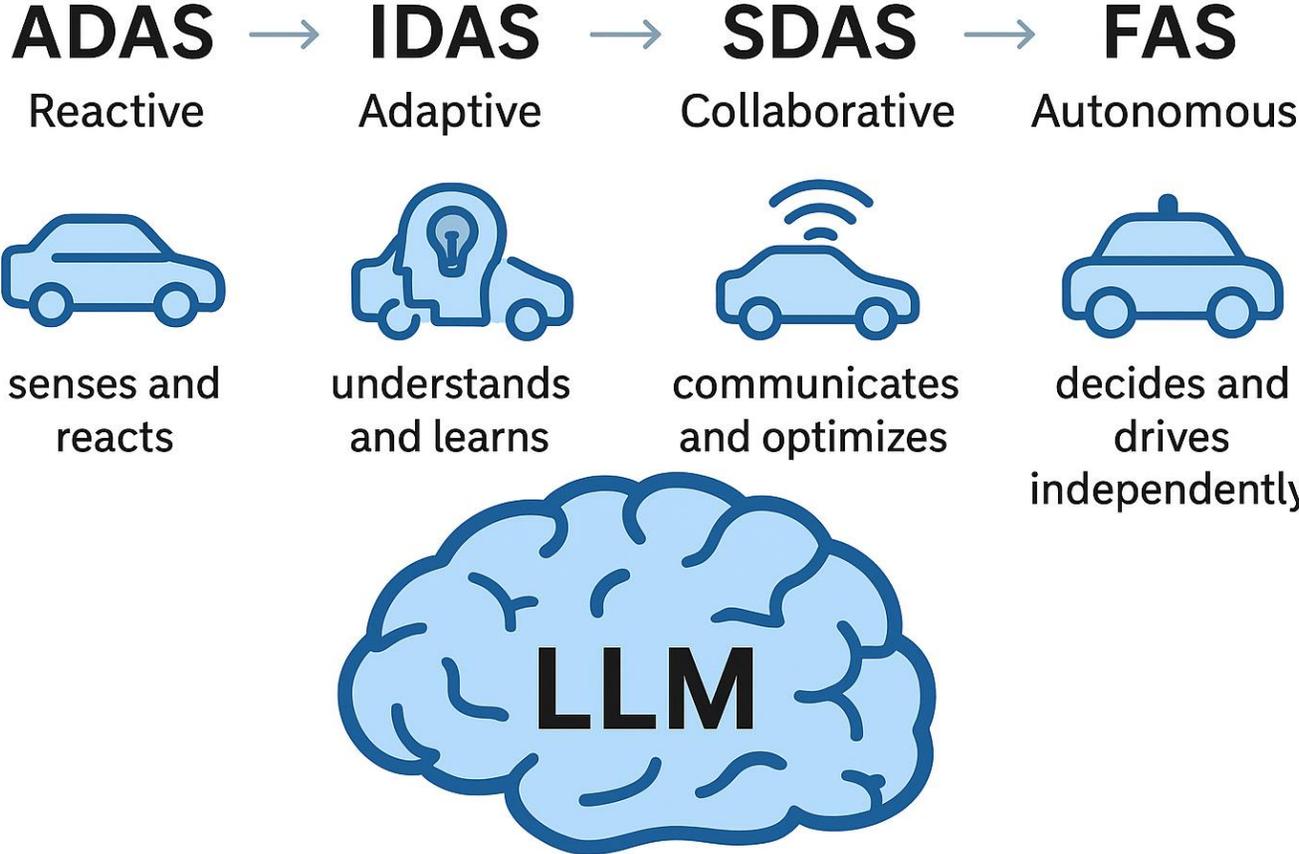
# 5. Foundations of Large Language Model



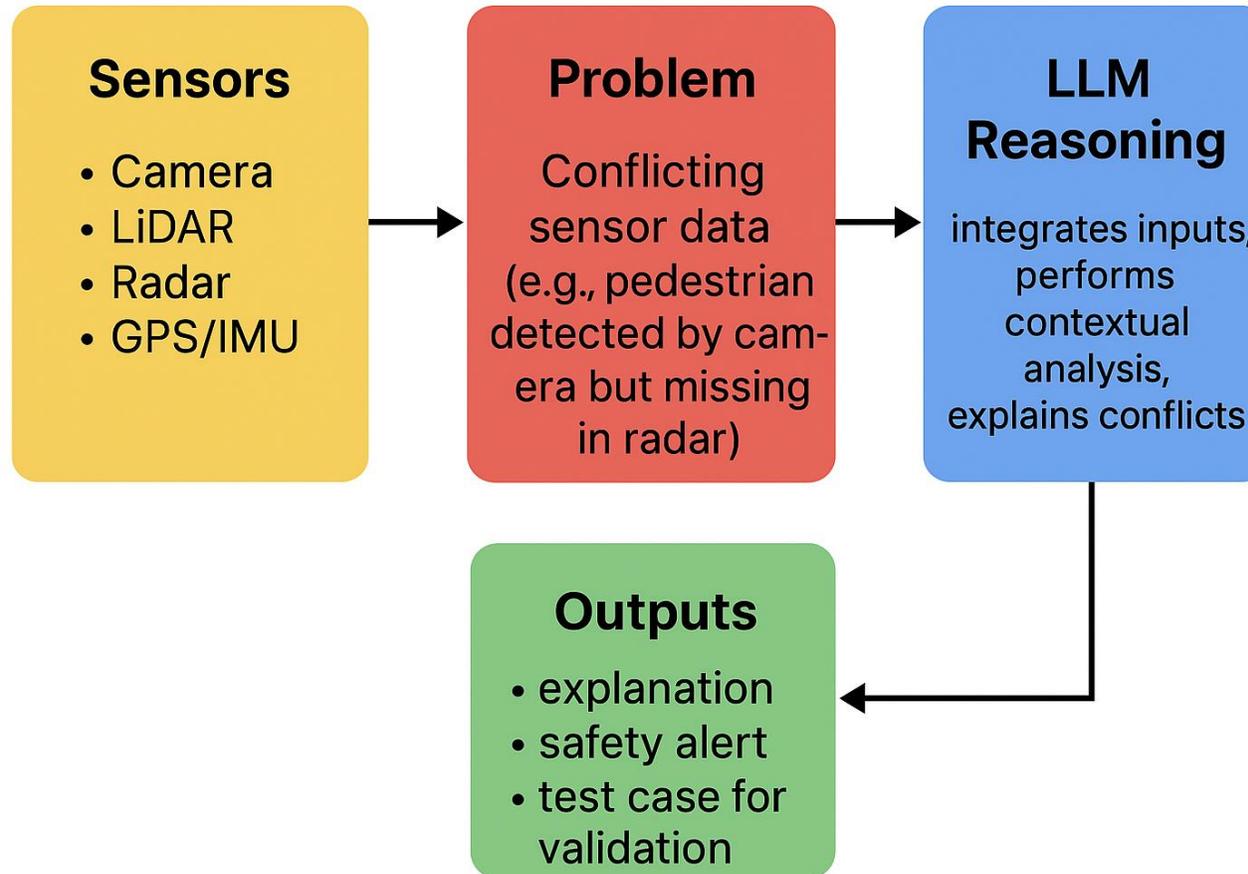
# 5. Foundations of Large Language Model



# 6. LLMs for the Automotive Domain



# 6. LLMs for the Automotive Domain

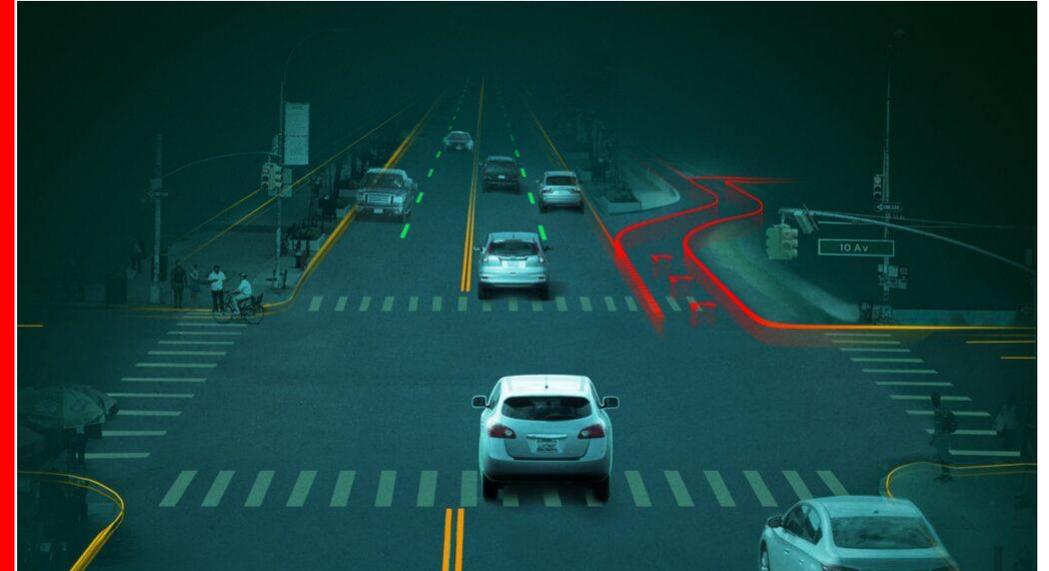


# 6. LLMs for the Automotive Domain

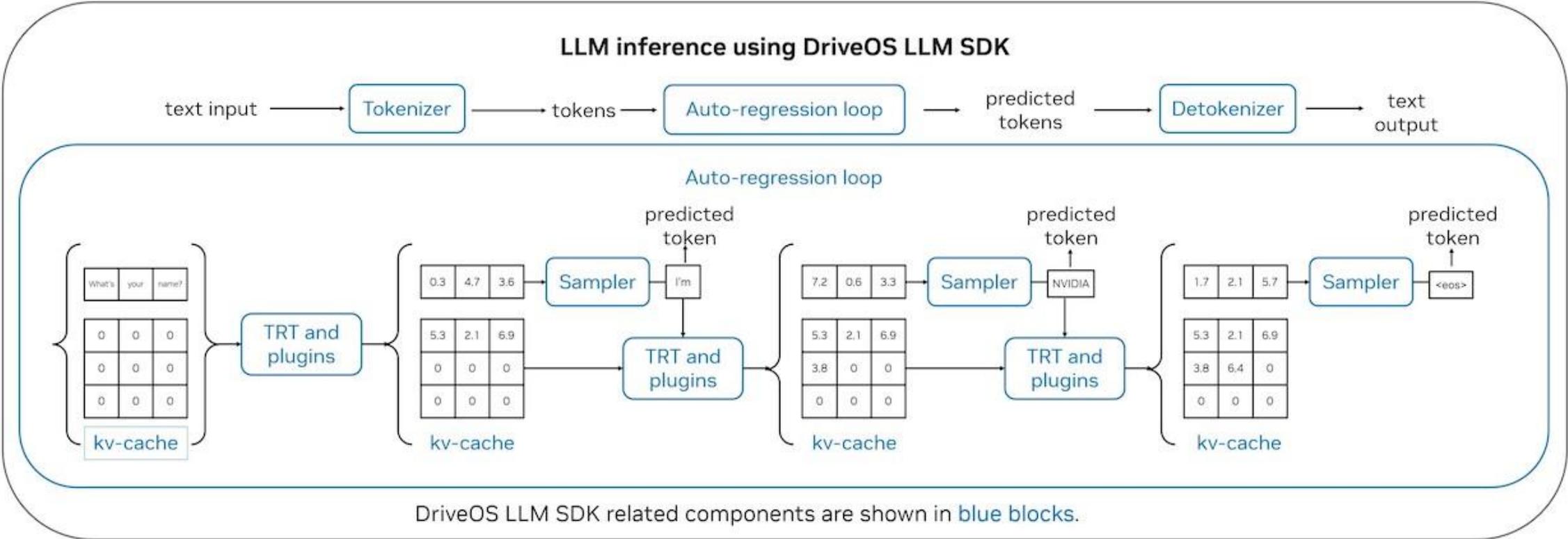
1. Data Sources (Vehicle Ecosystem)
2. Preprocessing and Representation
3. Large Language Model (LLM) Core
4. Applications in Automotive Systems
5. Human-in-the-Loop Outputs

## 6. LLMs for the Automotive Domain

Large Language Models (LLMs) demonstrate strong generalization in natural language processing, powering applications such as translation, digital assistants, recommendation systems, code generation, and cybersecurity. In automotive domains, demand is rising for LLM-based solutions in both autonomous driving and in-cabin features. However, deploying LLMs and Vision-Language Models (VLMs) on resource-constrained automotive platforms remains a critical challenge.



# 6. LLMs for the Automotive Domain



# 7. SLMs for the Automotive Domain

- A **Small Language Model (SLM)** is a **lightweight neural language model** designed to perform natural-language understanding, reasoning, or generation with **low computational cost**, making it suitable for **embedded, edge, or resource-constrained devices**.
- Compared to LLMs, an SLM typically has:
  - **fewer parameters** (50M to ~3B)
  - **lower memory footprint**
  - **faster inference**
  - **lower power consumption**
  - ability to run **on-device** or **in real time**
- SLMs maintain many capabilities of LLMs - such as question answering, summarization, and basic reasoning—but with optimized architectures so they can run **without requiring cloud computing**.

# 7. SLMs for the Automotive Domain

## Data Sources



Preprocessing

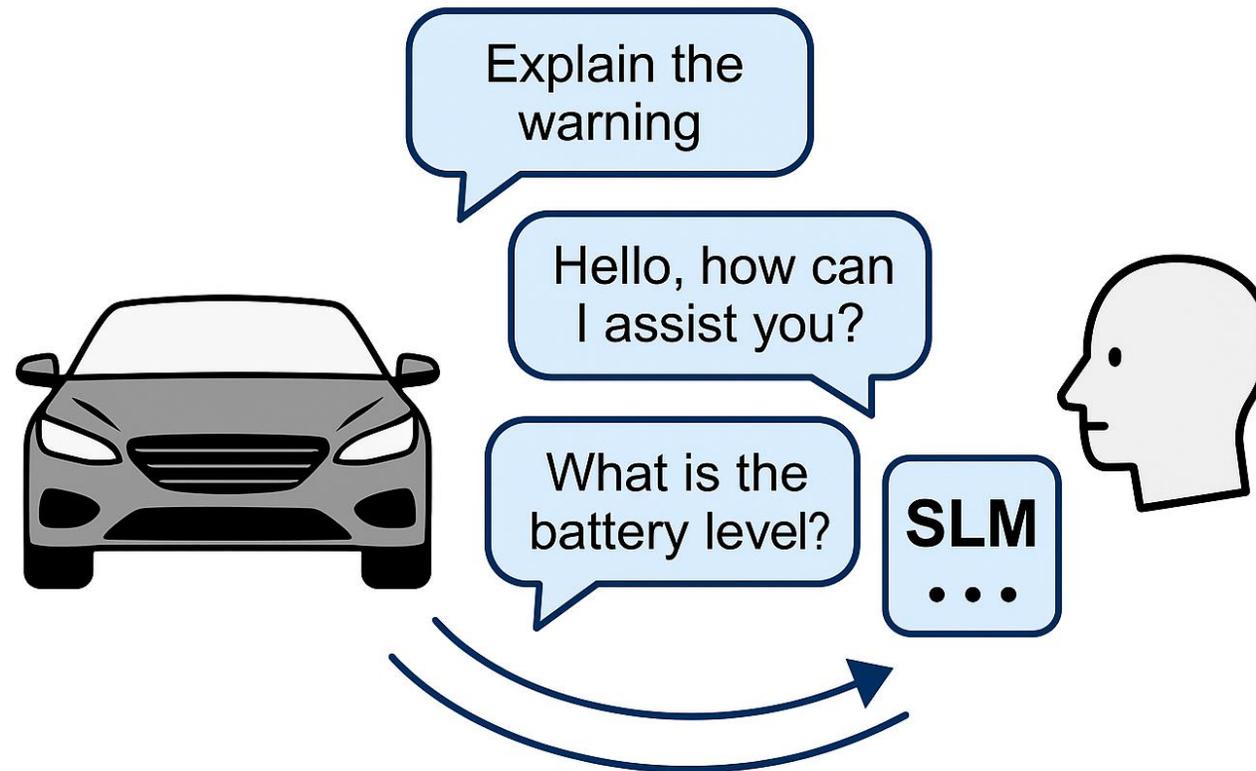
Tokens e Embeddings

## Applications

- Scenario Classification
- Anomaly Explanation
- Test Generation
- Human-Machine Interaction

# 7. SLMs for the Automotive Domain

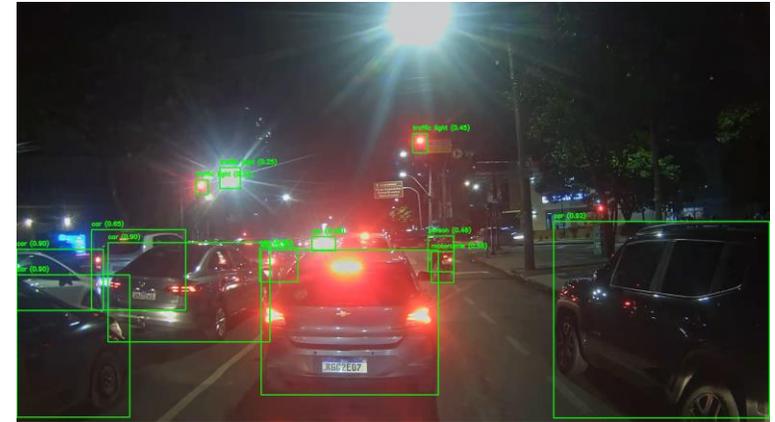
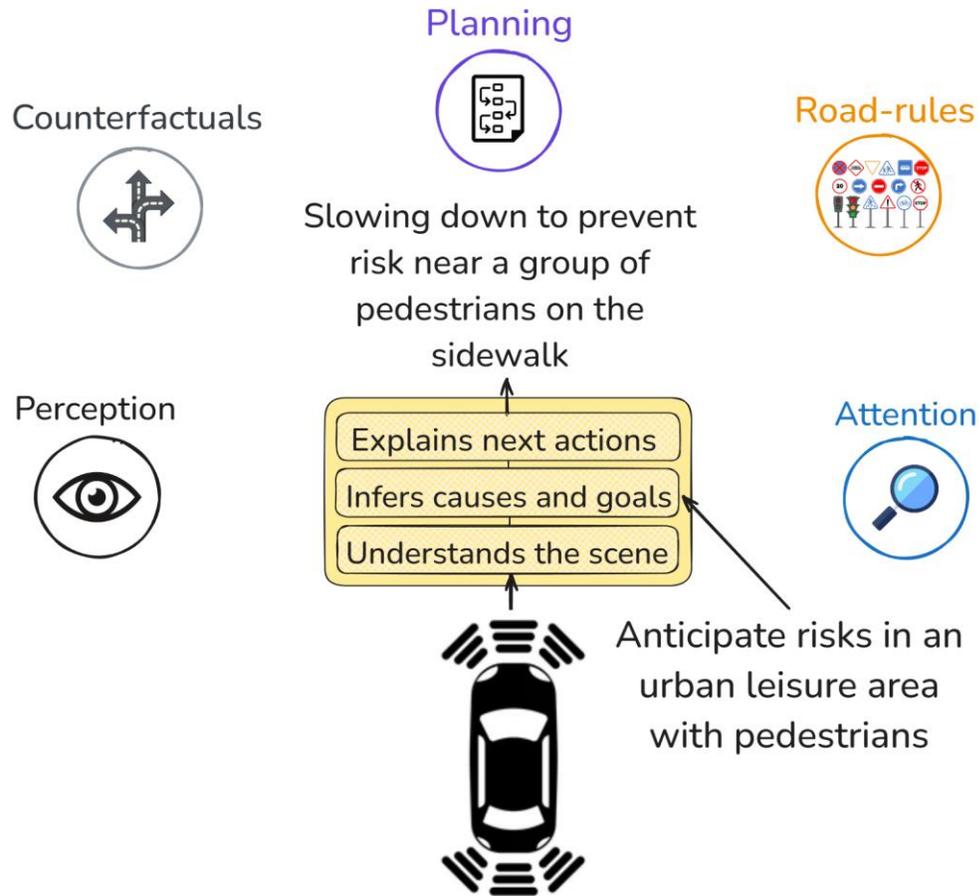
## SLMs for Human-Machine Interaction



# 8. Our Contributions in LLMs for the Automotive

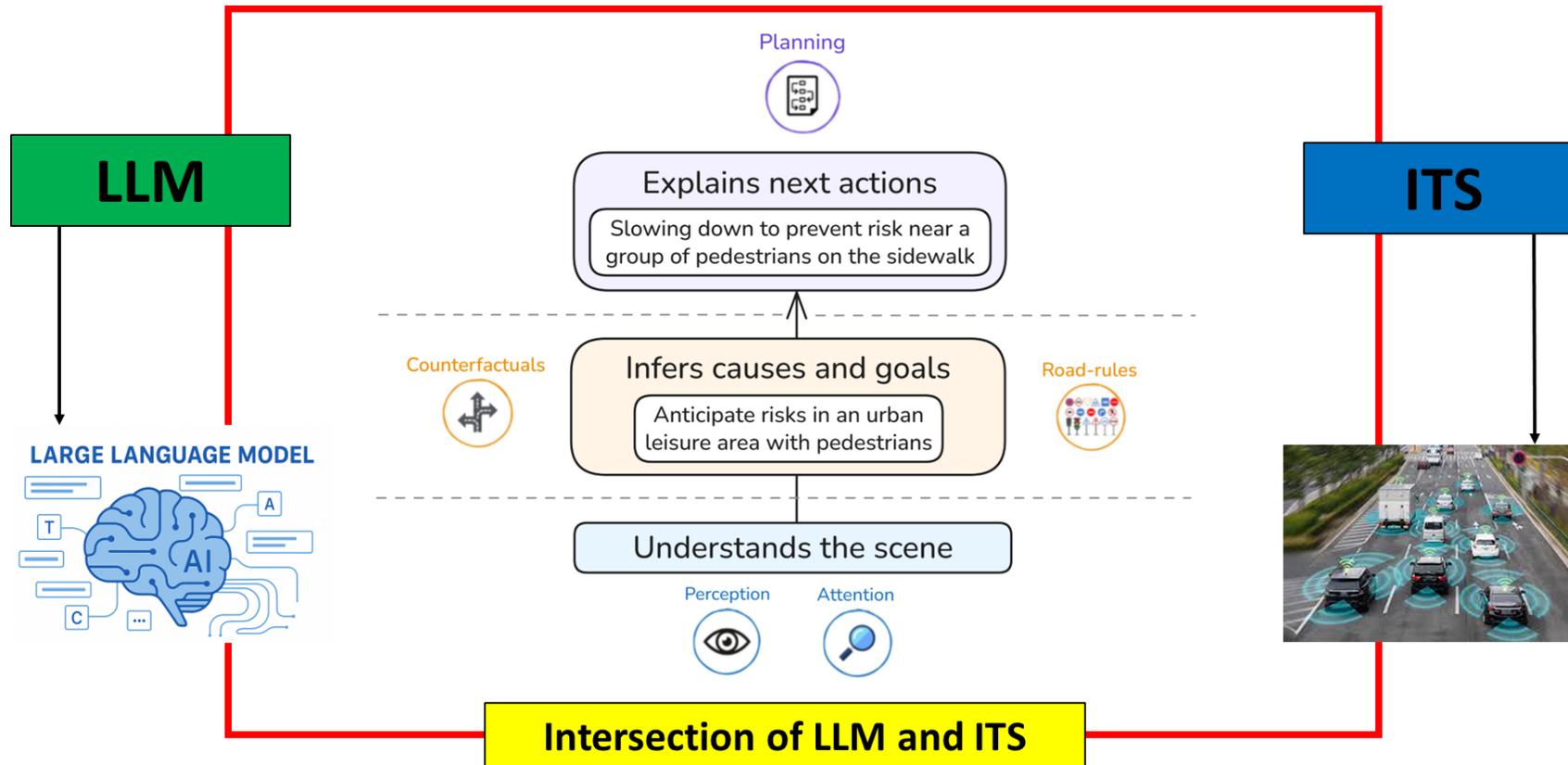
- **Conference:** IEEE ISIE 2025 – Toronto - CA
- **Title:** LLM-Powered Framework for Interpretable Traffic Rule Processing in Autonomous Driving (UTFPR-PG and TMU)

LLMs  
for  
driving  
assistance.



# 8. Our Contributions in LLMs for the Automotive

- **Conference:** IEEE ISGT 2025 – Dubai - UAE
- **Title:** Multimodal Large Language Model Framework for Safe and Interpretable Grid-Integrated EVs (UTFPR-PG, TMU, and UofT)



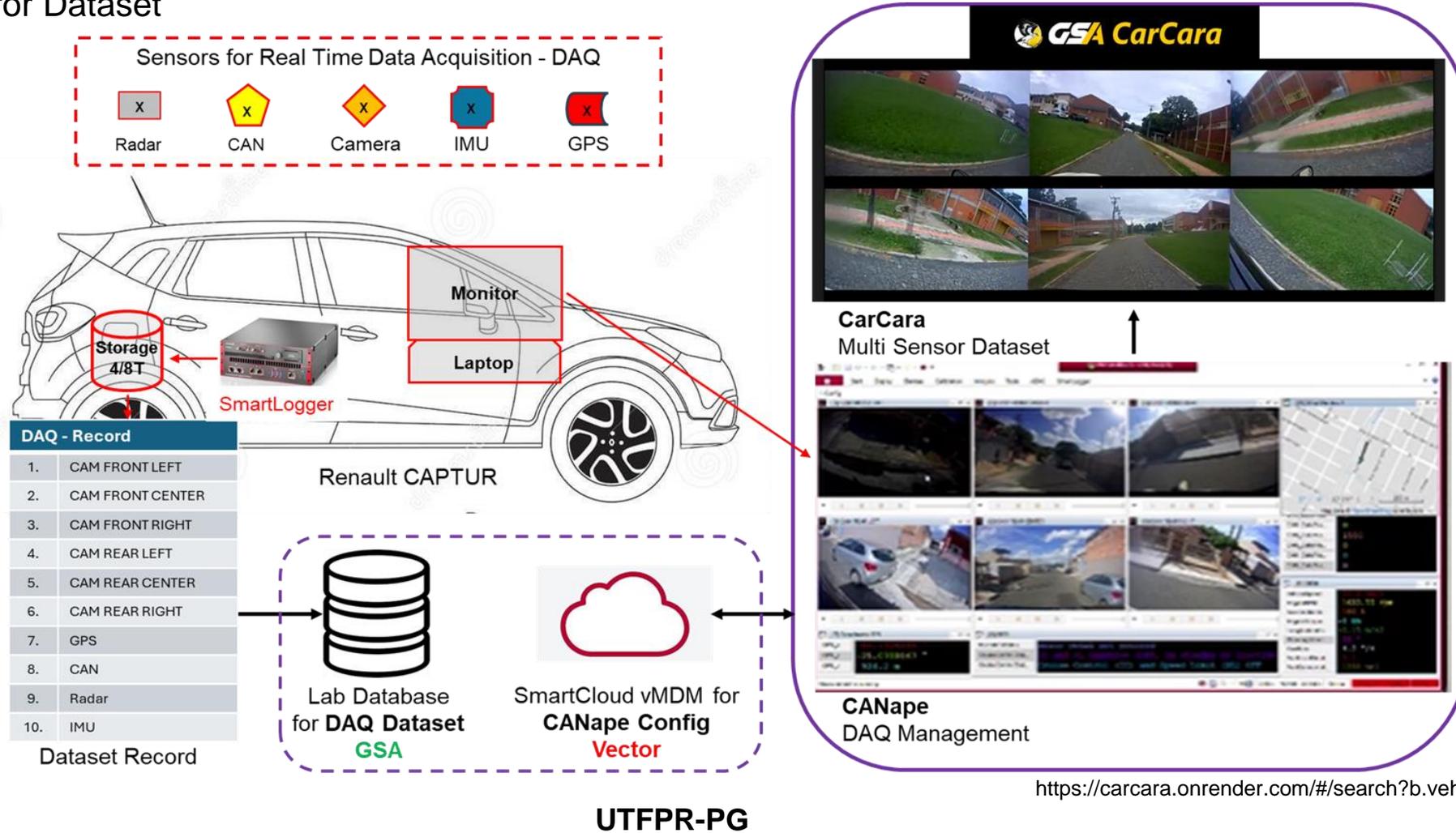
# 8. Our Contributions in LLMs for the Automotive

- **CarCara**
  - GSA has vehicles for DAQ



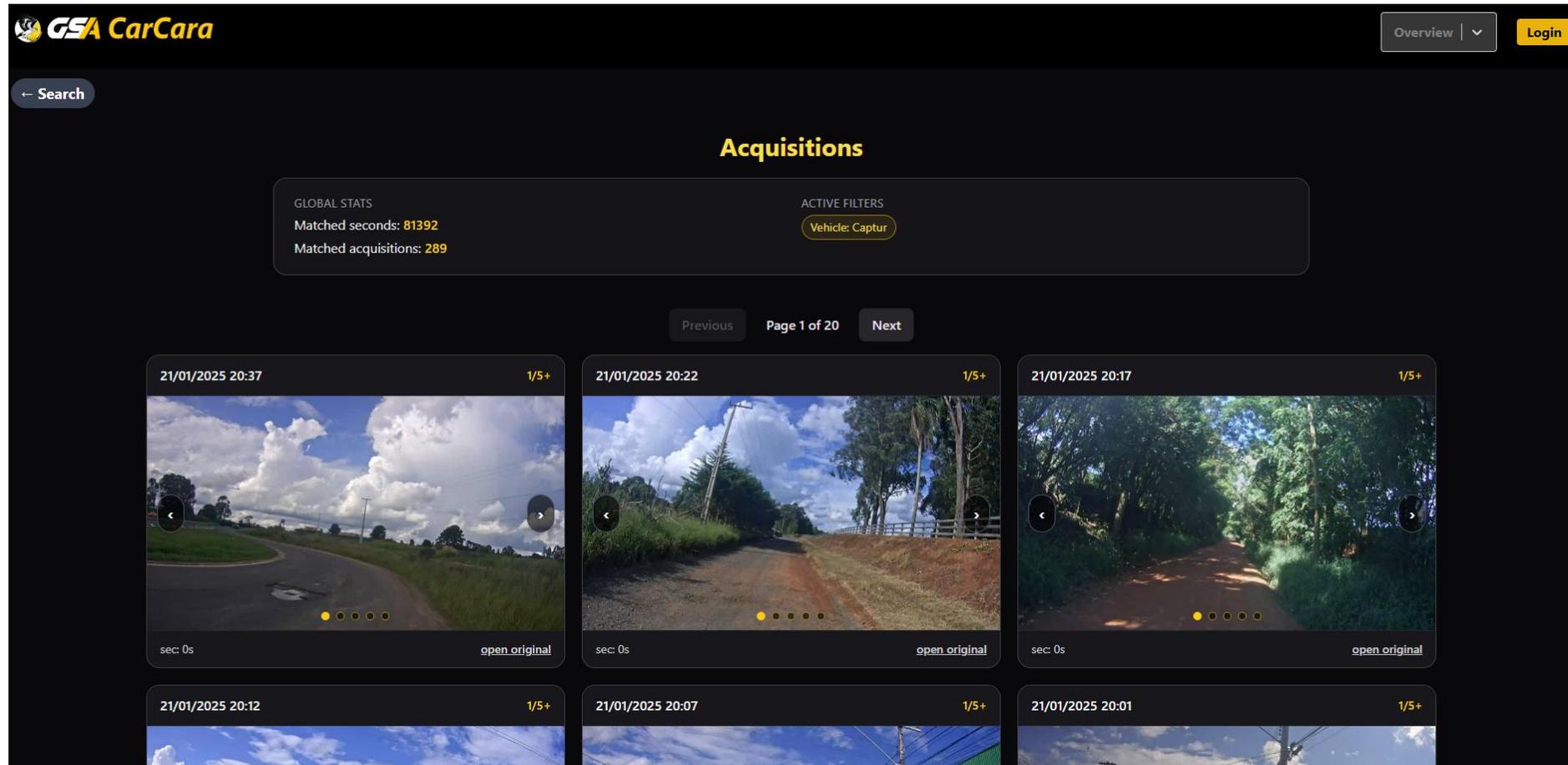
# 8. Our Contributions in LLMs for the Automotive

- CarCara
  - DAQ for Dataset



# 8. Our Contributions in LLMs for the Automotive

- CarCara
  - Powered by AI



# 9. Potential Use Cases

1. Sensor Data Fusion and Conflict Resolution
2. Autonomous Driving Decision Support
3. Natural Language Human-Vehicle Interaction
4. Predictive Maintenance and Diagnostics
5. Cybersecurity Threat Detection and Response
6. Test Case Generation for ADAS/AV Validation
7. Driver Behavior Monitoring and Alerts
8. Automated Documentation and Compliance Reports
9. Fleet Management and Operational Optimization
10. Context-Aware In-Vehicle Assistants

# 10. Expected Benefits



# 11. Challenges and Limitations

| Challenge Area             | Key Limitation  |
|----------------------------|---|
| Data Complexity            | Heterogeneous, high-dimensional, temporal multimodal data                 |
| Semantic Understanding     | Ambiguity, lack of domain knowledge, limited context reasoning            |
| Computational Requirements | Large model size, inference latency, edge deployment constraints          |
| Data Annotation            | High labeling cost, rare events, noisy sensor data                        |
| Interpretability           | Black-box outputs, limited explainability in safety-critical applications |
| Generalization             | Domain shift, rare events, multi-agent interactions                       |
| System Integration         | Requires hybrid architectures, complex validation pipelines               |
| Regulatory and Security    | Privacy, cybersecurity risks, compliance with safety standards            |



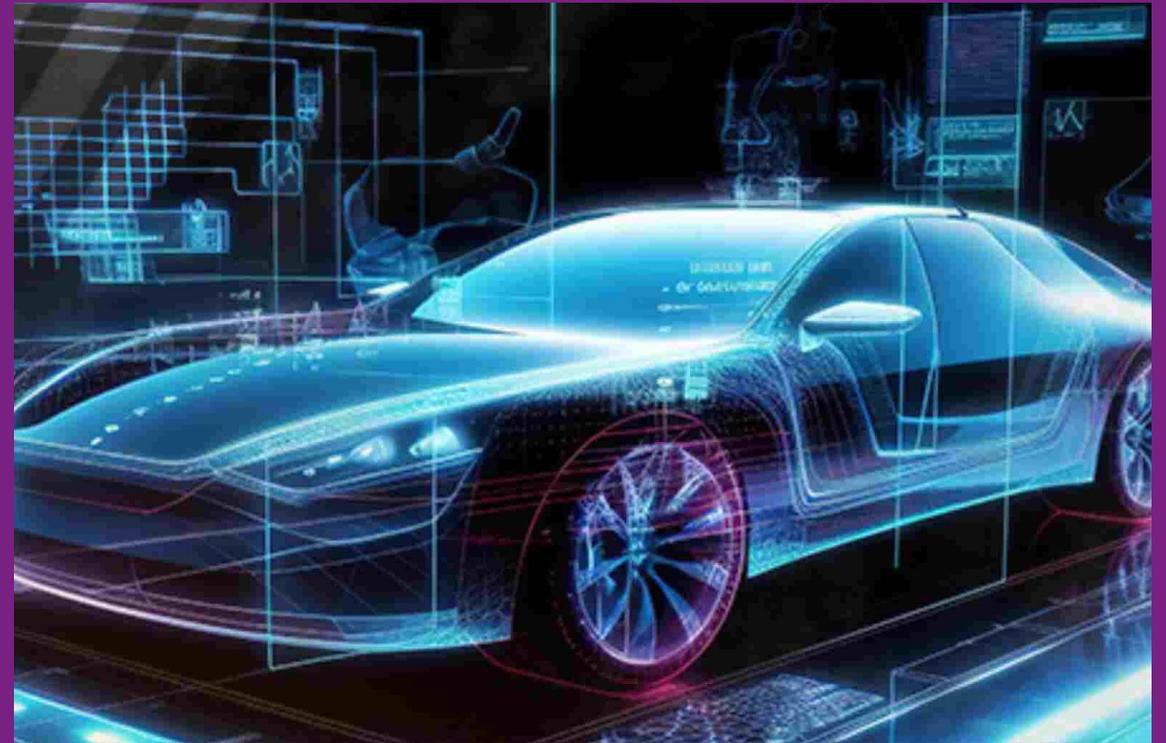
**CHALLENGES**



**LIMITATIONS**

# 12. Future Perspectives

The future of LLMs in autonomous and semi-autonomous vehicle datasets lies in their ability to provide context-aware, explainable, and real-time reasoning across complex multi-modal data, enhance testing and safety validation, enable fleet intelligence, and support regulatory compliance. With continued research in efficient deployment and multi-modal integration, LLMs could transform how autonomous systems interpret, reason, and act on their data.



# 13. References

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